### Goldman Research Sachs

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**Global Technology** 

# Robotaxi

### China's Robotaxi market - the road to commercialization

With 500,000 Robotaxis expected to be operating across 10+ cities in China by 2030, we believe the question is no longer if L4 autonomous technology is ready, but one of how companies will commercialize the rapid pace of autonomous development. We see Robotaxis as one of the earliest and most visible avenues to commercialization of the autonomous technology, with growing consumer acceptance across large Tier 1 cities, a tightening supply of human drivers as the fleets mature and drivers retire, and with Government and insurance industry as enablers to support growth. We see both a sizeable TAM opportunity ahead – US\$47bn by 2035, as well as a path to profitability, modelling positive gross margins in early 2026 for Tier 1 cities. Key factors to watch:

- 1 Decreasing costs of hardware and algorithms: Our forecast for China's Robotaxi TAM of \$47bn by 2035E vs. \$54mn in 2025 is driven by decreasing costs of hardware and algorithms and lowering operating costs for fleet owners. The form factor is a swing factor: Robotaxis have the potential to transform productivity of time spent in cars, turning vehicles into entertainment hubs or private workspace, gains that may significantly increase consumer demand. Supportive Government policies/licensing, and the development of insurance for the industry are both needed to support growth. Accident rates remain a crucial swing factor for expanding customer acceptance and reputation risk.
- 2 Unit economics turning profitable, encouraging more suppliers: By 2035E, we expect revenues per Robotaxi in Tier-1 cities to reach \$31,000, higher than current ride hailing vehicles, due to longer operating hours and efficient route planning. We model positive gross margin at the vehicle level by 2026E/2031E/2034E in T1/T2/other cities.

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## China Robotaxi TAM Snapshot



Source: Company data, Goldman Sachs Global Investment Research

# China Robotaxi TAM in details

Exhibit 2: China Robotaxi TAM: increasing from US\$54mn to US\$47bn in 2025-35E

China Robotaxi TAM (US\$m)	2024	2025E	2026E	2027E	2028E	2029E	2030E	2031E	2032E	2033E	2034E	2035
nina Robotaxi TAM	10	54	206	606	1,703	4,313	11,711	18,637	26,306	33,924	40,538	46,568
er-1 city Robotaxi er-2 city Robotaxi	6 3	40 12	156 29	484 66	1,457 181	3,335 785	8,064 2,835	11,351 5,374	14,189 9,272	16,492 14,334	17,866 19,161	19,457 23,150
her cities	1	3	21	56	65	193	812	1,912	2,845	3,098	3,512	3,961
ix	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
er-1 city Robotaxi er-2 city Robotaxi	60% 29%	73% 22%	76% 14%	80% 11%	86% 11%	77% 18%	69% 24%	61% 29%	54% 35%	49% 42%	44% 47%	429 509
ther cities	10%	22% 5%	10%	9%	4%	4%	24% 7%	10%	11%	42% 9%	9%	99
y operators	10	54	206	606	1,703	4,313	11,711	18,637	26,306	33,924	40,538	46,568
ony Al	1	9	31	88	371	1,305	4,964	7,803	10,918	12,807	14,631	16,416
aidu	9	33 13	124 51	378 140	569	757 2,251	1,247 5,501	2,119	3,073 12,315	3,687 17,430	4,204	4,624
hers Robotaxi Revenues per vehicle	2024	2025E	2026E	2027E	764 2028E	2,251 2029E	2030E	8,714 2031E	2032E	2033E	21,704 2034E	25,529 2035
evenues per vehicle (US\$ '000)	8	13	18	23	24	24	25	25	25	25	25	25
er-1 city	9	14	20	26	26	28	30	31	31	31	31	31
er-2 city	8	12	16	17	17	17	19	20	21	22	22	22
ther cities	5 <b>107%</b>	8 <b>62%</b>	11 <b>36%</b>	12 <b>25%</b>	13 <b>6%</b>	13 <b>0%</b>	15 <b>3%</b>	17 <b>0%</b>	18 <b>1%</b>	19 <b>1%</b>	20 <b>0%</b>	20 -19
er-1 city	40%	51%	43%	29%	0%	6%	6%	3%	2%	0%	0%	09
er-2 city	104%	59%	33%	5%	1%	1%	10%	4%	6%	5%	2%	0
ther cities	133%	56%	31%	13%	3%	4%	15%	9%	8%	4%	4%	0
By distance ares per km (US\$)												
er-1 city	0.40	0.40	0.40	0.40	0.38	0.36	0.33	0.33	0.32	0.31	0.31	0.30
er-2 city	0.32	0.32	0.32	0.32	0.30	0.27	0.26	0.25	0.24	0.24	0.23	0.23
ther cities	0.26	0.26	0.26	0.26	0.24	0.22	0.21	0.20	0.19	0.19	0.19	0.18
DY%	00/	0%	00/	00/	00/	00/	00/	20/	00/	00/	00/	
er-1 city	0% 0%	0% 0%	0% 0%	0% 0%	-6% -8%	-6% -8%	-6% -5%	-2% -5%	-2% -2%	-2% -2%	-2% -2%	-2 -2
er-2 city ther cities	0%	0%	0%	0%	-8%	-8%	-5% -5%	-5% -5%	-2% -2%	-2% -2%	-2% -2%	-2' -2'
perating distance per day (km)												
er-1 city	94	101	138	179	191	216	244	257	268	273	278	28
er-2 city ther cities	95 84	107 94	137 117	144 132	158 149	173 168	200 204	219 235	236 258	253 274	264 290	27 29
ravelled distance per day (km)	04	94	117	132	149	100	204	235	256	2/4	290	29
er-1 city	200	220	300	360	360	380	420	440	440	440	440	44
er-2 city	225	275	350	350	350	375	475	475	525	550	550	55
ther cities	240	240	300	330	330	420	510	510	600	630	630	63
dization rate	47%	46%	46%	50%	53%	57%	58%	59%	61%	62%	63%	65
er-1 city er-2 city	42%	39%	39%	41%	45%	46%	42%	46%	45%	46%	48%	49
ther cities	35%	39%	39%	40%	45%	40%	40%	46%	43%	44%	46%	47
evenues per vehicle day (US\$)	22	36	49	62	66	66	68	68	68	69	69	6
er-1 city	38	41	56	72	72	77	82	84	86	86	86	86
er-2 city	30 22	34	44 30	46	47 35	47 37	52 42	54	57 50	60 52	61 54	6
ther cities perating days	22	24	30	34	35	3/	42	46	50	52	54	54
er-1 city	250	350	365	365	365	365	365	365	365	365	365	365
er-2 city	250	350	365	365	365	365	365	365	365	365	365	365
ther cities	250	350	365	365	365	365	365	365	365	365	365	365
By orders umber of orders per day												
er-1 city	14	15	21	27	27	27	28	29	29	29	29	29
er-2 city	14	15	19	20	20	20	20	20	21	22	22	22
ther cities	14	15	16	17	17	17	18	18	19	20	21	2
SP per order (US\$)												
er-1 city	2.6 2.2	2.6 2.3	2.6 2.3	2.7 2.3	2.7 2.3	2.9 2.4	3.0 2.6	3.0 2.7	3.0 2.7	3.0 2.7	3.0	3.0
er-2 city			2.3					2.1	2.1			0.0
			1 0	2.0	2.1	22	23	2.6	2.6		2.8	2.8
ther cities	1.5	1.6	1.9	2.0	2.1	2.2	2.3	2.6	2.6	2.6		2.0
			1.9 2026E	2.0 2027E	2.1 2028E	2.2 2029E	2.3 2030E	2.6 2031E	2.6 2032E		2.8	2.
ther cities eet size Robotaxi volume obotaxi volume (units '000)	1.5 2024 1.3	1.6 2025E 4.1	2026E 11.4	2027E 26.9	2028E 71.0	2029E 179.3	2030E 473.5	2031E 756.3	2032E 1,054.1	2.6 2033E 1,347.7	2.8 2.6 2034E 1,609.4	2035 1,861.
ther cities eet size Robotaxi volume bobtaxi volume (units '000) er-1 cities	1.5 2024 1.3 0.7	2025E 4.1 2.8	2026E 11.4 7.7	2027E 26.9 18.5	2028E 71.0 55.3	2029E 179.3 119.1	2030E 473.5 270.4	2031E 756.3 368.9	2032E 1,054.1 451.2	2.6 2033E 1,347.7 526.5	2.8 2.6 2034E 1,609.4 571.0	2035 1,861. 621.
ther cities eet size Robotaxi volume  botaxi volume (units '000)  er-1 cities  beijing	1.5 2024 1.3 0.7 0.2	1.6 2025E 4.1 2.8 0.9	2026E 11.4 7.7 2.8	2027E 26.9 18.5 6.3	2028E 71.0 55.3 20.7	2029E 179.3 119.1 44.2	2030E 473.5 270.4 105.9	2031E 756.3 368.9 134.8	2032E 1,054.1 451.2 172.2	2.6 2033E 1,347.7 526.5 205.3	2.8 2.6 2034E 1,609.4 571.0 221.8	2035 1,861. 621. 243.
ther cities eet size Robotaxi volume botaxi volume (units '000) er-1 cities Beijing Shanghai	1.5 2024 1.3 0.7 0.2 0.1	1.6 2025E 4.1 2.8 0.9 0.5	2026E 11.4 7.7 2.8 0.7	2027E 26.9 18.5 6.3 2.6	2028E 71.0 55.3 20.7 8.9	2029E 179.3 119.1 44.2 20.5	2030E 473.5 270.4 105.9 53.2	2031E 756.3 368.9 134.8 86.5	2032E 1,054.1 451.2 172.2 114.5	2.6 2033E 1,347.7 526.5 205.3 137.3	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4	2035 1,861. 621. 243. 171.
ther cities eet size Robotaxi volume  botaxi volume (units '000)  er-1 cities  beijing	1.5 2024 1.3 0.7 0.2	1.6 2025E 4.1 2.8 0.9	2026E 11.4 7.7 2.8	2027E 26.9 18.5 6.3	2028E 71.0 55.3 20.7	2029E 179.3 119.1 44.2	2030E 473.5 270.4 105.9	2031E 756.3 368.9 134.8	2032E 1,054.1 451.2 172.2	2.6 2033E 1,347.7 526.5 205.3	2.8 2.6 2034E 1,609.4 571.0 221.8	2. 2035 1,861. 621. 243. 171. 115.
ther cities eet size Robotaxi volume botaxi volume (units '000) er1 cities selijing Shanghai suangzhou shenzhen er-2 cities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4	1.6 2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0	2032E 1.054.1 451.2 172.2 114.5 93.4 71.0 446.2	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2	2.035 1,861. 621. 243. 171. 115. 91. 1,037.
ther cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing Shanghai Suangzhou Shenzhen er-2 cities ther cities	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3	2. 2035 1,861. 621. 243. 171. 115. 91. 1,037. 202.
ther cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing Shanghai Guangzhou Shenzhen er-2 cities ther cities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0	2032E 1.054.1 451.2 172.2 114.5 93.4 71.0 446.2	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2	2.035 1,861 621. 243 171 115 91. 1,037 202
ther cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing Beijing Beijing Buangzhou Shenzhen er-2 cities ther cities Shared Mobility and Penetration (Taxi + Ride	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  hailing + Robo	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60%	2032E 1.054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39%	2.6 2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9	2.8 2.6 2034E 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19%	2035 1,861. 621. 243. 171. 115. 91. 1,037. 202.
ther cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing Shanghai Guangzhou Shenzhen er-2 cities ther cities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95% halling + Robo 4.6	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3	2.035 1,861 621. 243 171 115 91. 1,037 202
ther cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing Shanghai Buangzhou Shenzhen er-2 cities ther cities Shared Mobility and Penetration (Taxi + Ride mared mobility fleet volume by city (m) er-1 cities er-2 cities	1.5  2024  1.3  0.7  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178%	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 657.3 163.9 28%  6.7 1.6 3.4	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7	2.355 1.861. 621. 243. 171. 115. 91. 1,037. 202. 16
ther cities eet size Robotaxi volume Dotaxi volume (units '000) er-1 cities Beijing Shanghal Buangzhou Shenzhen er-2 cities ther cities Y% Shared Mobility and Penetration (Taxi + Ride ared mobility fleet volume by city (m) er-1 cities er-2 cities ther cities	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 224% taxi) 4.8 1.1 2.6 1.2	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0	2080E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1	2032E 1.054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5	2. 2035 1,861. 621. 243. 171. 115. 91. 1,037. 202. 166 7. 1. 3.
her cities ever ities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95% halling + Robo 4.6 1.0 2.5 1.1	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 1.2 6%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2%	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7%	2082E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7%	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28%  6.7 1.6 3.4 1.7 6%	2.8 2.6 2034E 1,609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6%	2038 1.861. 621. 243. 171. 115. 91. 1,037. 202. 160. 7.
her cities evet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities leijing shanghai Suangzhou Shenzhen er-2 cities her cities Shared Mobility and Penetration (Taxi + Ride lared mobility fleet volume by city (m) er-1 cities er-2 cities her cities er-1 cities er-1 cities er-1 cities er-1 cities er-1 cities er-2 cities her cities	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1  10%  4.6	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 4.8 1.1 2.6 1.2 6% 4.8	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1.6	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 2.8 1.0 2% 5.1	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.2 2.9 1.2 7.6 5.5	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7	2.8 2.6 2034E 1,609.4 571.0 – 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0	2.333 1.861. 621. 243. 171. 115. 91. 1,037. 202. 166 7. 1. 3. 1. 5.
her cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Belijing Shanghai Buangzhou Shenzhen er-2 cities ther cities Yy'% Shared Mobility and Penetration (Taxi + Ride lared mobility fleet volume by city (m) er-1 cities er-2 cities ther cities Yy'% In a company to the company to the company to the cities Yy'% In a company to the company to the company to the cities Yy'% In a company to the company to th	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95% halling + Robo 4.6 1.0 2.5 1.1 10% 4.6 3.2	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 6% 4.8 3.5	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 3.6	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 5.0 3.6	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2% 5.1 3.6	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9	2032E 1.054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0	2.8 2.6 2.034E 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1	2.333 1,861. 621. 243. 171. 115. 91. 1,037. 202. 166 7. 1. 5. 7. 4.
her cities  set size  Robotaxi volume  Robotaxi volume (units '000)  er-1 cities  selijing  shanghal  suangzhou  shenzhen  er-2 cities  her cities  Shared Mobility and Penetration (Taxi + Ride  lared mobility fleet volume by city (m)  er-1 cities  er-2 cities  cher cities  her cities  y'%  arrand mobility fleet volume by operation (m  de hailing fleet  xi fleet	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 224% taxi) 4.8 1.1 2.6 6% 4.8 3.5 1.4 0.0	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5 1.4 0.0	2027/E 26.9 18.5 6.3 2.6 6.5 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 3.6 1.4 0.0	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 5.0 3.6 1.4 0.1	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2.9 5.1 3.6 1.4 4.0 2.0 5.1	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 7.0 6.3 1.5 7.0 6.3 1.5 7.0 6.3	2.6  2033E 1.347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3	2.8 2.8 2.6 2.034E 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1 1.3 1.6	2038 1,861. 621. 243. 171. 115. 91. 1,037. 2022. 166 7. 1. 4. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.
her cities event size Robotaxi volume Robotaxi volume (units '000) er-1 cities Reliping Relip	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  hailing + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0  10%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 1.2 6% 4.8 3.5 1.4 0.0 6%	11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5 1.4 0.0 2.6	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 3.6 1.4 0.0 2%	2023E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 5.0 1.4 0.1	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2% 5.1 1.4 0.2 2%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.88 7%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3 3.9 1.3	2.6  2033E 1.347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 1.3 6%	2.8 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6	2. 2034 1,861. 621. 243. 171. 115. 91. 1,037. 202. 16 7. 1. 5. 7. 4. 1. 1. 5.
her cities  estaize  Robotaxi volume  Bobotaxi volume (units '000)  er-1 cities  leijing  shanghai  buangzhou  shenzhen  er-2 cities  her cities  Shared Mobility and Penetration (Taxi + Ride  leared mobility fleet volume by city (m)  er-1 cities  er-1 cities  er-1 cities  er-1 cities  er-2 cities  her cities  in citie	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0  10%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 4.8 1.1 2.6 1.2 6 4.8 3.5 1.4 0.0 6%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5 1.4	2027E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2.0 3.6 1.4 0.0 2.0 1.9	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 5.0 3.6 1.4 0.1 1%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2.5 5.1 1.0 2.5 3.6 1.4 4.1 2.8 3.6 3.6 3.6 3.6 3.6 3.6 3.6 3.6 3.6 3.6	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7% 9%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3 3.9 1.1 77%	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 1.3 6% 6%	2.8 2.6 2.03dE 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1 1.3 1.6 6 6% 23%	2. 2038 1.861. 621. 243. 171. 115. 91. 1,037. 202. 166 7. 1. 3. 1. 5. 7. 4. 1. 1.
her cities eet size Robotaxi volume botaxi volume (units '000) er-1 cities sleijing shanghai suangzhou shenzhen er-2 cities cher cities yy'% Shared Mobility and Penetration (Taxi + Ride lared mobility fleet volume by city (m) er-1 cities er-2 cities cher cities yy'% shared mobility fleet volume by city (m) er-1 cities yy'% lared mobility fleet volume by operation (m de hailing fleet xi fleet bototaxi fleet yy'% sbotaxi penetration rate er-1 cities er-1 cities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95% halling + Robo 4.6 1.0 2.5 1.1 10% 4.6 0.2 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 1.2 6% 4.8 3.5 1.4 0.0 6% 0.3%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 176% 4.9 1.2 2.6 4.9 3.5 1.4 0.0 2% 0.7 3.0 1.2 1.8 1.9 1.2 2.6 4.9 1.2 2.6 4.9 1.2 2.6 4.0 4.0 4.0 4.0 4.0 4.0 4.0 4.0 4.0 4.0	2027/E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 2% 1.4 0.0 2%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 4%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2% 5.1 3.6 1.4 0.2 2% 5.9 9%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7% 9% 19%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7% 13%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3 1.7 93.9 1.3 1.1 7% 1.7%	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 6% 20% 33%	2.8 2.6 2.034E 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1 1.3 1.6 6% 23.4 23.4 23.4 23.4 23.4 23.4 23.4 23.4	2. 203: 1,861. 621. 243. 171. 115. 91. 1,037. 202. 16. 7. 1. 5. 7. 4. 1. 5. 25.
her cities eet size Robotaxi volume Dobotaxi volume (units '000) er-1 cities Beijing	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.1  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0  10%  0%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% (axi) 4.8 1.1 2.6 1.2 6% 4.8 3.5 1.4 0.0 6% 0.3% 0.3% 0.2%	11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5 1.4 0.0 2% 1.4 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0	2027E 26.9 18.5 6.3 2.6 6.8 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 3.6 1.4 0.0 2% 1% 2% 1%	2023E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 3.6 1.4 0.1 1% 4% 4%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2.8 5.1 3.6 1.4 0.2 2.8 3.7 3.8 9.8 9.8 9.9 9.8	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7% 9% 19% 19% 20%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7% 13% 25%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 7,0 6.3 3.9 1.1 7,0 6.3 1.7 7,0 6.3 2,0 7,0 8,0 8,0 8,0 8,0 8,0 8,0 8,0 8,0 8,0 8	2.6  2033E 1.347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 1.3 6% 20% 33%	2.8 2.6  2034E  1.609.4E  571.0  221.8  152.4  111.1  85.6  859.2  179.3  19%  7.0  1.7  3.5  1.8  6%  7.0  4.1  1.3  1.6  6%  23%  34%	2 203 1.861 621 243 171 115 91 1,037 202 16 7 7 7 1 1 3 3 1 1 1 5 1 1 1 1 1 1 1 1 1 1 1 1
her cities  set size  Robotaxi volume  Bobotaxi volume (units '000)  ar-1 cities  selijing  shanghai  suangzhou  shenzhen  ar-2 cities  her cities  Shared Mobility and Penetration (Taxi + Ride  sared mobility fleet volume by city (m)  ar-1 cities  ar-2 cities  her cities  yr%  shared mobility fleet volume by operation (m  de hailing fleet  si fleet  blotaxi fleet  yr%  si fleet  botaxi penetration rate  ar-1 cities  er-1 cities  er-1 cities  penedration (m  de hailing fleet  si fleet  blotaxi penetration rate  ar-1 cities  er-1 cities  her cities	1.5  2024  1.3  0.7  0.1  0.2  0.1  0.4  0.2  55%  hailing + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0  10%  0%  0%  0%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 1.2 6% 4.8 3.5 1.4 0.0 6% 0.3% 0.2% 0.2% 0.1%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2.7 0.0 0.7 3.5 1.4 0.0 0.7 3.5 1.4 0.7 3.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1	2027/E 26.9 18.5 6.3 6.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 1.4 0.0 2% 1% 1% 1%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 5.0 3.6 1.4 0.1 1% 4% 4% 4% 4% 3%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2% 5.1 0.2 2% 9% 9% 9% 9%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7% 9% 19%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7% 13% 25% 24%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3 3.9 1.3 1.1 7.0 29% 29% 27%	2.6  2033E  1.347.7  526.5  205.3  137.3  104.9  78.9  657.3  163.9  28%  6.7  1.6  3.4  1.7  4.0  1.3  1.3  6%  20%  33%  33%  31%  31%  35%	2.8 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6	2. 2031 1.861. 621. 243. 171. 115. 91. 1,037. 202. 16 77. 4. 4. 1. 5. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3.
see stize Robotaxi volume Beet size Robotaxi volume (units '000) Robotaxi Robotaxi (Taxi + Ride lared mobility fleet volume by city (m) Robotaxi (units '000) Robotaxi Robo	1.5  2024  1.3  0.7  0.2  0.1  0.2  0.4  0.2  95%  halling + Robo  4.6  1.0  2.5  1.1  10%  4.6  3.2  1.4  0.0  10%  0%  0%  0%  0%  0%  0%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 4.8 1.1 2.6 1.2 6 4.8 3.5 1.4 0.0 0% 0.3% 0.2% 0.1% 0.5% 0.5%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 1.1 2% 4.9 3.5 1.4 0.0 2% 1.9 1.9 3.5 1.9 1.9 3.5 1.9 1.9 3.5 1.9 1.9 3.5 1.9 1.9 1.9 1.9 1.9 1.9 1.9 1.9 1.9 1.9	2027E 26.9 18.5 6.3 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 6.0 1.4 0.0 2% 1% 2% 1% 1% 3%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 4% 4% 4% 4% 4%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2.8 5.1 0.2 2.8 9% 9% 9% 9% 9% 9%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 52.7 164% 5.5 1.4 2.9 1.2 7% 5.5 3.7 1.4 0.5 7% 9% 19% 20% 14% 23%	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7% 13% 25%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 3.2 1.5 7% 6.3 3.9 1.1 77% 29% 29% 29% 29% 29% 31%	2.6  2033E 1,347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 1.3 6% 33% 33% 33% 33%	2.8 2.6 2.034E 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1 1.3 1.6 6% 33% 34% 34% 34%	2. 2083 1.861. 621. 1.861. 621. 1.71. 1.15. 91. 1.037. 1.6 1.5 1.6 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5
ther cities est size Robotaxi volume botaxi volume (units '000) er-1 cities selijing Shanghai Suangzhou Shenzhen er-2 cities ther cities yy'% Shared Mobility and Penetration (Taxi + Ride nared mobility fleet volume by city (m) er-1 cities er-2 cities ther cities yy'% sared mobility fleet volume by operation (m de hailing fleet ixi fleet bototaxi fleet by's botaxi fleet by's selijing Shanghai Suangzhou Shanghai Suangzhou Shenzhen er-2 cities	1.5  2024 1.3 0.7 0.2 0.1 0.2 0.1 0.4 0.2 95% halling + Robo 4.6 1.0 2.5 1.1 10% 4.6 0.0 0% 0% 0% 0% 0% 0% 0%	1.6  2025E 4.1 2.8 0.9 0.5 1.0 0.5 1.0 0.3 224% taxi) 4.8 1.1 2.6 6% 4.8 3.5 1.4 0.0 6% 0.3% 0.2% 0.1% 0.5% 0.3% 0.2% 0.1% 0.5% 0.3% 0.0%	2026E 11.4 7.7 2.8 0.7 3.0 1.2 1.8 1.9 178% 4.9 1.2 2.6 4.9 3.5 1.4 0.0 2% 0.7 3.0 1.2 1.8 1.9 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0	2027/E 26.9 18.5 6.3 2.6 6.6 3.0 3.9 4.6 136% 5.0 1.2 2.7 1.1 2% 5.0 2% 1% 1% 1% 1% 1% 1% 3% 2% 1% 3% 2%	2028E 71.0 55.3 20.7 8.9 17.6 8.1 10.7 5.1 164% 5.0 1.3 2.7 1.0 1% 4% 4% 4% 4% 4% 4% 4% 4% 4% 4% 4% 4% 4%	2029E 179.3 119.1 44.2 20.5 34.8 19.6 45.8 14.4 152% 5.1 1.3 2.8 1.0 2% 5.1 3.6 1.4 0.2 2% 9% 9% 6% 14% 10% 2%	2030E 473.5 270.4 105.9 53.2 63.5 47.8 150.4 55.7 164% 5.5 1.4 2.9 1.2 7% 6.5 3.7 1.4 0.5 7% 9% 20% 20% 20% 21% 22% 23% 23% 23% 23% 23% 23% 23	2031E 756.3 368.9 134.8 86.5 84.4 63.2 274.0 113.5 60% 5.9 1.5 3.1 1.4 7% 5.9 3.8 1.3 0.8 7% 137% 22% 24% 22% 31% 29% 9%	2032E 1,054.1 451.2 172.2 114.5 93.4 71.0 446.2 156.7 39% 6.3 1.5 7% 6.3 3.2 1.5 7% 6.3 1.5 29% 29% 29% 29% 29% 32% 31%	2.6  2033E  1.347.7 526.5 205.3 137.3 104.9 78.9 657.3 163.9 28% 6.7 1.6 3.4 1.7 6% 6.7 4.0 1.3 1.3 6% 20% 33% 33% 33% 33% 31% 35% 31% 35%	2.8 2.6 2034E 1.609.4 571.0 221.8 152.4 111.1 85.6 859.2 179.3 19% 7.0 1.7 3.5 1.8 6% 7.0 4.1 1.3 1.6 6% 23% 34% 34% 34% 33% 35% 34% 34% 34% 34% 33% 35% 34% 34% 34% 34% 34% 34% 34% 34% 34% 33% 35% 34% 34% 34% 34% 34% 34% 34% 34% 34% 34	2. 2033 1,861. 621. 1243. 171. 115. 91. 1,037. 202. 166 7. 1. 1. 5. 7. 4. 1. 1. 5. 355 355 355 355 355
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Source: Company data, Goldman Sachs Global Investment Research

### Global Robotaxi TAM scenarios

Our Autonomous Vehicles (AVs) forecast implies that a global fleet of a few million commercial AVs used for rideshare could be on the road in 2030. Although this would comprise less than 1% of the global car parc of over 1 bn vehicles, it could result in a >\$25 bn market for personal mobility from robotaxis (depending on factors such as ASPs, trips per day, and average miles traveled per trip). We assume the international mix of the business affects revenue per trip in this 2030 scenario. More optimistic scenarios on utilization and ASPs would imply a \$100 bn+ market in 2030.

Exhibit 3: We estimate the market in 2030 for robotaxis could be >\$25 bn

			2030 market s	cenarios for rob				
Revenue	Trips per			Global A	√s in operation	(000s)		
per trip	robotaxi per day	150	750	1,350	2,000	2,650	3,300	4,000
\$5	5 2	\$548	\$2,738	\$4,928	\$7,300	\$9,673	\$12,045	\$14,600
	4	\$1,095	\$5,475	\$9,855	\$14,600	\$19,345	\$24,090	\$29,200
	6	\$1,643	\$8,213	\$14,783	\$21,900	\$29,018	\$36,135	\$43,800
	8	\$2,190	\$10,950	\$19,710	\$29,200	\$38,690	\$48,180	\$58,400
	10	\$2,738	\$13,688	\$24,638	\$36,500	\$48,363	\$60,225	\$73,000
	12	\$3,285	\$16,425	\$29,565	\$43,800	\$58,035	\$72,270	\$87,600
	14	\$3,833	\$19,163	\$34,493	\$51,100	\$67,708	\$84,315	\$102,200
\$7	7 2	\$767	\$3,833	\$6,899	\$10,220	\$13,542	\$16,863	\$20,440
	4	\$1,533	\$7,665	\$13,797	\$20,440	\$27,083	\$33,726	\$40,880
	6	\$2,300	\$11,498	\$20,696	\$30,660	\$40,625	\$50,589	\$61,320
	8	\$3,066	\$15,330	\$27,594	\$40,880	\$54,166	\$67,452	\$81,760
	10	\$3,833	\$19,163	\$34,493	\$51,100	\$67,708	\$84,315	\$102,200
	12	\$4,599	\$22,995	\$41,391	\$61,320	\$81,249	\$101,178	\$122,640
	14	\$5,366	\$26,828	\$48,290	\$71,540	\$94,791	\$118,041	\$143,080
\$9	2	ተባባራ	<b>#4 020</b>	\$8,870	¢12 140	¢17 /11	\$21,681	¢26.290
Φ\$	9 2	\$986 \$1,971	\$4,928 \$9,855	\$6,670 \$17,739	\$13,140 \$26,280	\$17,411 \$34,821	\$43,362	\$26,280 \$52,560
		\$2,957	\$14,783	\$26,609	\$39,420	\$54,621 \$52,232	\$65,043	\$78,840
	6 8	\$2,957 \$3,942	\$14,763 \$19,710	\$26,609 \$35,478	\$59,420 \$52,560	\$69,642	\$86,724	\$105,120
	10							
	10	\$4,928 \$5,013	\$24,638	\$44,348	\$65,700	\$87,053	\$108,405 \$130,086	\$131,400 \$157,690
		\$5,913	\$29,565	\$53,217	\$78,840	\$104,463 \$134,874	\$130,086 \$151,767	\$157,680
	14	\$6,899	\$34,493	\$62,087	\$91,980	\$121,874	\$151,767	\$183,960

Source: Company data, Goldman Sachs Global Investment Research

### (1) Market size? 700x China Robotaxi TAM growth in the next 10 years

We expect China's Robotaxi market to grow from US\$\$54 million in 2025 to US\$12 billion in 2030 and US\$47 billion in 2035 (Exhibit 4). The TAM will grow 757x in the 10 years of 2025-35, indicating a strong market opportunity. Revenue generation is mainly from riding fare charges, which we will discuss further in the revenue generation session of the report. Overall, we expect each Robotaxi can generate US\$69 per day by 2035 (vs. US\$36 in 2025), which will be higher than traditional ride-hailing vehicles which on average generate US\$28-56 (Rmb200-450) per day, due to longer operating times.

Exhibit 4: Robotaxi TAM in China: increasing to US\$47bn in 3035

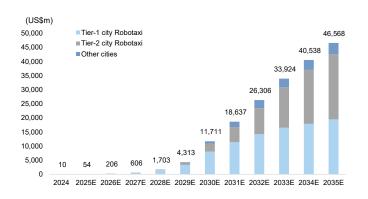
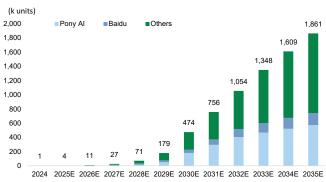


Exhibit 5: Robotaxi fleet in China: increasing to 1.9m by 2035, based on forecast of multiple robotaxi companies



Source: Company data, Goldman Sachs Global Investment Research

Source: Company data, Goldman Sachs Global Investment Research

We model China's total Robotaxi fleet size to grow from 4.1 thousand by 2025 to 0.5 million by 2030 and 1.9 million by 2035 (Exhibit 5). We expect the existing players, including Pony AI, WeRide, Baidu Apollo to continue to be among the major players, considering the high technological entry barrier and leaders' edge in algorithm, data, high definition map, operations, and partnership with the car OEMs and local governments. Robotaxis will be an effective supplement to China's public transport ecosystem, in our view, considering potential driver shortages due to the aging population.

Exhibit 6: China's total number of ride hailing vehicle, taxis and buses

('000)	Ride hailing vehicles	Taxi	Bus
('000)	Ride hailing vehicles	Taxi	Bus
2019	1,040	1,392	693
2020	1,120	1,394	704
2021	1,558	1,391	709
2022	2,118	1,362	703
2023	2,792	1,367	683
YoY %	Ride hailing vehicles	Taxi	Bus
2020	8%	0%	2%
2021	39%	0%	1%
2022	36%	-2%	-1%
2023	32%	0%	-3%

Source: Ministry of Transport of PRC

### (2) Penetration? 25% by 2035 to fill the labour gap of taxi drivers

**4 million drivers retiring by 2035, per our estimate.** A survey by Tsinghua University shows that taxi drivers aged above 46 accounted for 31% of the ride hailing drivers in China in 2021. With 13 million active ride-hailing and taxi drivers in China, those within the 46-65 age group in 2021 will mostly retire by 2035 (aged over 60), suggesting that 4 million drivers will retire during 2021-2035. We expect the labor gap to be partially fulfilled by our estimated 1.9m units of robotaxis (Exhibit 7).

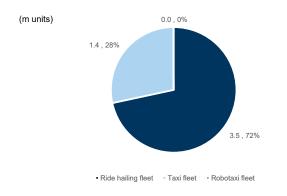
Exhibit 7: We estimate there will be 4m of taxi/ ride hailing drivers to retire by 2035

Ago group	Age structure of shared mobility drivers as of 2021					
Age group	%	# of drivers (m)	Remarks			
56-65	6%	0.8	Retiring by 2025			
46-55	25%	3.2	Retiring by 2035			
26-45	65%	8.5				
25 and below	4%	0.5				
Total	100%	13.0				
# of drivers retiring by 2035		4.0				
# of robotaxi per GSe by 2035		1.9				
# of new drivers needed		2.2				

Source: Research report on travel platforms in China's first-tier cities by Tsinghua University, Goldman Sachs Global Investment Research, Company data

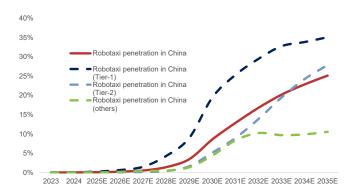
The driver shortage has become increasingly prevalent in China due to demographic change and a declining interest among young people in pursuing this profession (according to media reports). In 2024, multiple cities including Shenzhen, Hangzhou, Ningbo and Chengdu announced to extend the maximum age of taxi drivers to 65 years old, in order to cope with the potential driver shortages.

Exhibit 8: Shared mobility fleet in China (2025E, m units)



Source: Company data, Goldman Sachs Global Investment Research

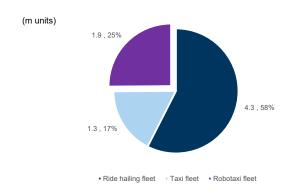
Exhibit 10: Penetration cycle of Robotaxis in China: Tier-1/ Tier-2/ Others cities



Robotaxi penetration = Robotaxi fleet / (Robotaxi + traditional taxi + shared riding vehicle fleet)

Source: Company data, Goldman Sachs Global Investment Research

Exhibit 9: Shared mobility fleet in China (2035E, m units)



Source: Company data, Goldman Sachs Global Investment Research

Exhibit 11: Penetration cycle of Robotaxis in China: vs. NEV and L4/L5 technology



Robotaxi penetration = Robotaxi fleet / (Robotaxi + traditional taxi + shared riding vehicle fleet)

Source: Company data, Goldman Sachs Global Investment Research

The penetration of robotaxi to the overall shared mobility fleet in China will increase from <1% in 2025, gradually to 9% by 2030 and accelerate to 25% by 2035E, in our view. The initial ramp up of robotaxi adoption will be gradual, as we

expect robotaxi players to stay prudent, expanding carefully to test the algorithm and ensuring safety. They will also need time to build up a customer feedback system and improve service quality.

### (3) Elements of success? Technology and experience

Technology and experience remain the competitive moat. We believe that mileage, disengagement, and accident rate are important elements to measure the readiness of a robotaxi player to conduct large scale deployment: (1) **Testing mileage**: mileage is important, as it indicates experience and successful track record. (2) **Miles per disengagement:** The need for human interventions reflect the difference in the level of intelligence. (3) **Active traffic accident rate:** Accident rate will be a key metric to monitor when robotaxis begin large scale business operations. Traditional taxis can cause 0.036 fatal accident per bn km traveled (<u>Link</u>), and robotaxis need to have a better performance than that.

Exhibit 12: Commonly used tech terms to measure robotaxi's safety level

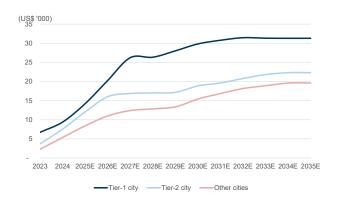
Key metrics	How to benchmark and measure the safety level
Accumulated testing mileages	The higher the better, with more experiences
Average testing speed	The higher the better, showing company's capabilites to ensure safety amid high speed
MPD	Miles per Disengagement, the lower the better
MPC	Miles per Collision, the lower the better
Remote assistant	Number of vehicles per remote assistant staff could handle, the lower the better
Basic safety function	AEB (Autonomous Emergency Braking), FCW (Forward Collision Warning) etc.
Emergency	Robotaxi capabilities to handle emergency
Cybersecurity	C-V2X, automotive cloud safety test

Source: Company data, Goldman Sachs Global Investment Research

### (4) Revenues generation? Up to \$31k per vehicle in tier-1 cities by 2035E

### Exhibit 13: Robotaxi revenues per vehicle

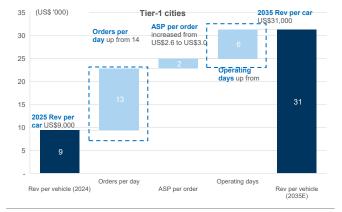
Increasing from US\$5k~9k per year in 2024 to US\$20k~31k in 2035E



Source: Company data, Goldman Sachs Global Investment Research

# Exhibit 14: Robotaxi in Tier-1 cities: Revenue per vehicle increases to US\$31k by 2035E

Largely driven by increasing orders per day and increasing operating days



Source: Company data, Goldman Sachs Global Investment Research

The revenues of robotaxis are mainly contributed by the fares charged from

passengers. In our analysis, we evaluate robotaxi's revenue generation by (1) the number orders per day, (2) the ASP per order, and (3) the number of operating days per year. We estimate that by 2035E, Revenue per vehicle can reach US\$31,000/US\$22,000/US\$20,000 in tier-1 / tier-2/ other cities in China.

### Breaking down the source of per vehicle revenue growth

Orders per day up to 29 orders by 2035E: Pony Al's average daily orders per vehicle has reached 15 in 2024, surpassing the average ride-hailing drivers in Shenzhen (12 orders per day in 2H24, but below full time taxi drivers (25 orders per day in 2H24. We estimate the industry level orders per day to be 15/ 15/ 15 in tier-1/ tier-2/ other cities in 2025, increasing to 29/ 22/ 21 in 2035E. Robotaxis can take more orders than traditional taxis given their longer operation hours - each robotaxi can run up to 22 hours per day with 2 hours for maintenance and charging in the future, per our channel checks, compared to up to 15 hours for traditional ride-hailing vehicles/ taxis.

**ASP per order up to US\$3.0 by 2035E:** The pricing of robotaxi benchmarks are lower than that of traditional ride hailing vehicles/ taxis, and vary across cities. We expect the fares per km to decline in the long term, however, we expect the ASP per order to continue to increase, from US\$2.6/ 2.3/ 1.6 in tier-1/ tier-2/ other cities in 2025E to US\$3.0/ 2.8/ 2.6 in 2035E, driven by larger operating area and longer trips per order.

**Number of operating days up to 365 by 2035E:** We expect the total number of operation days to be 350 days in 2025E, increasing to 365 days in 2026-35E in order to make full use of the vehicles.

### (5) Costs reduction? Down to \$19k per vehicle in tier-1 cities in 2035E

#### Exhibit 15: Robotaxi COGS per vehicle

Decreasing from ~US\$20k per year in 2025E to ~US\$19k in 2035E, in tier-1/ tier-2/ other cities

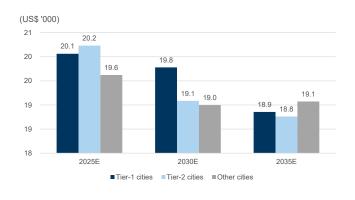
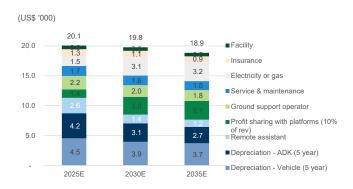


Exhibit 16: Robotaxi COGS per vehicles in Tier-1 cities: Vehicle and ADK price deceasing, but operating costs and profit sharing increasing



Source: Company data, Goldman Sachs Global Investment Research

Source: Company data, Goldman Sachs Global Investment Research

We expect per vehicle COGS of a robotaxi to decline from US\$20.1k to US\$18.9k per year in 2025-35E in tier-1 cities (<u>Exhibit 16</u>). However, we expect some operating costs to increase as fleet scales, partially offset by the continuous downward trend of vehicle and intelligent driving ADK (Assessment and Deployment Kit) costs.

Exhibit 17: Robotaxi COGS per vehicles in Tier-1 cities: Vehicle costs deceasing, but operating costs increasing

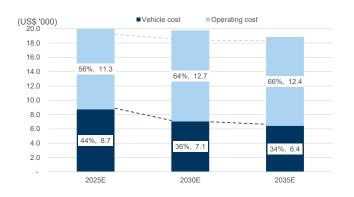
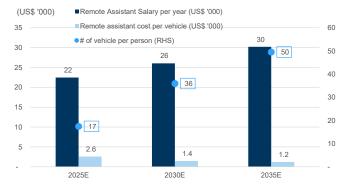


Exhibit 18: Remote Assistant cost per vehicle per year in Tier-1 cities: decrease from US\$2,600 per vehicle to US\$1,200

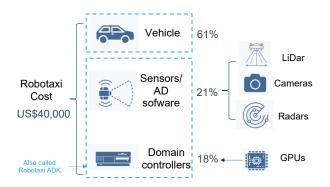


Source: Company data, Goldman Sachs Global Investment Research

Source: Company data, Goldman Sachs Global Investment Research

**Operating costs have a mixed trend.** Among operating expenses, we expect the spending on remote assistant to decrease as technology evolves, requiring less monitoring and intervention (Exhibit 18). Chinese robotaxi players expect per remote staff to monitor 50-100 vehicles at the same time in an ideal case vs. now <= 20 vehicle per person. On the other hand, we expect maintenance, charging, cleaning and operation costs to increase as the fleet scales, as these should be a function of usage and the number of trips per day. Profit sharing costs with platforms will also increase along with the increase of robotaxi revenues, given the common practice of taking 10% of GMV to share with the 3rd party ride hailing platforms who provide traffic and accessibility to users.

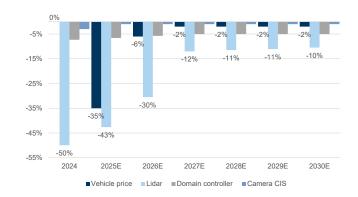
Exhibit 19: Robotaxi vehicle costs breakdown



A typical robotaxi comes with 4x LiDar, 11x cameras, 2x radars, and domain controllers with 1000+ TOPS computing

Source: Company data, Goldman Sachs Global Investment Research

Exhibit 20: Typical price down trend of robotaxi components



Vehicle price according to GS China robotaxi TAM; Lidar price based on GSe ASP of Hesai; Domain controller price based on GSe ASP of Desay SV's high end product lines; Camera CIS based on GSe 8MPx CIS ASP of Will Semi

Source: Company data, Goldman Sachs Global Investment Research

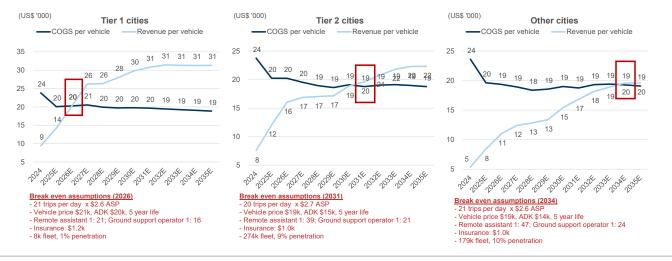
**Robotaxi vehicle costs declining.** The Robotaxi hardware costs will quickly trend down in 2025 as major players release new models that come with lower costs and ready for mass production. For example, Pony Al's Gen7 models will be rolling out in 2H25 with 70% BoM costs savings, WeRide's GXR model launched in Oct 2024 also costs lower than its previous generation, and Baidu's Apollo Go Gen 6 model costs only US\$29,000, or 60% lower than its Gen5 (According to Media reports). **We expect the** 

vehicle cost (basic vehicle + intelligent driving ADK) of China's robotaxi industry to be at US\$44,000 in 2025E, decreasing to US\$35,000 by 2030E and US\$32,000 by 2035E. The faster than expected Robotaxi car models expansion to local car models or mid / low-priced models, or faster than expected pricing decline under fierce competition could bring potential upside to our vehicle costs estimates.

We estimate 61% of the vehicle cost to be contributed by the vehicle itself, followed by 21% by sensors/ autonomous driving software and 18% by domain controllers (<u>Exhibit 19</u>). We expect further price decrease across major components, as shown in <u>Exhibit 20</u>, and the software costs will be lower as more robotaxis are put into use to share the R&D spending.

# (6) Unit economics? Profit making by 2026E/ 31E/ 34E in Tier-1/ -2 / other cities

Exhibit 21: Breakeven roadmap in Tier-1/ Tier-2/ Other cities



Source: Company data, Goldman Sachs Global Investment Research

Tier-1/Tier-2/ Other cities in China to see positive gross profit per vehicle in 2026E/ 2031E/ 2034E, respectively (Exhibit 21). Along with the increasing revenues and decreasing COGS per vehicle, we expect the average per vehicle gross profits of robotaxis in China to turn positive before 2035E. Tier-1 cities will achieve positive profits by 2026E with 0% gross margin, increasing to 34%/ 40% by 2030E /35E. Tier-2 cities' breakeven point will be 2031E with 4% gross margin, increasing to 16% by 2035E. Tier-3 cities will not see positive income per vehicle until 2034E (2% gross margin), which will increase to 3% by 2035E.

#### **Exhibit 22: Unit economics in details**

Unit economics summary (Tier-1	cities)				
(US\$ '000)	2025E	2030E	2035E	GM break-even year (2026)	Remarks
Revenues	14.2	29.8	31.3	20.3	21 orders per day x \$2.6 ASP
# of orders	15	28	29	21	
ASP (US\$)	2.6	3.0	3.0	2.6	
Fleet size ('000)	3	270	622	8	The increase of coverage area supports orders/ ASP growth
Penetration rate	0%	19%	35%	1%	
Vehicles D&A (5 year)	4.5	3.9	3.7	4.3	Vehicle price: \$21k
ADK D&A (5 year)	4.2	3.1	2.7	3.9	ADK price: \$20k
Remote assistant	2.6	1.4	1.2	2.2	Annual salary \$22k, 2 shifts, 21 vehicles per person
Profit sharing with platforms	1.4	3.0	3.1	2.0	10% of revenues to platforms like Didi/ Amap
Ground support operator	2.2	2.0	1.8	2.2	Annual salary \$22k, 1.5 shifts, 16 vehicles per person
Service & maintenance	1.7	1.6	1.5	1.7	Cleaning, testing and maintenance
Electricity or gas	1.5	3.1	3.2	2.2	\$0.02 per km for EV
Insurance	1.3	1.1	0.9	1.2	Already lower than human drivers
Facility	0.6	0.6	0.6	0.6	Facility and warehouse for parking and maintenance
cogs	20.1	19.8	18.9	20.3	
Among which: Fixed cost	15.4	12.1	11.0	14.4	D&A, remote assistant, ground support, facility, insurance
Variable cost	4.6	7.6	7.9	5.9	Profit sharing, service & maintenance, Electricity
Among which: Fixed cost	77%	61%	58%	71%	
Variable cost	23%	39%	42%	29%	
Gross profit	(5.9)	10.0	12.4	(0.0)	
GM	-41%	34%	40%	0%	
R&D expenses	270.0	12.2	5.0	135.0	
% R&D to Revenues	1900%	41%	16%	666%	
SG&A expenses	80.0	6.4	3.0	40.0	
% SG&A to Revenues	563%	21%	10%	197%	
Operating profit	(355.9)	(8.5)	4.4		OP break-even will take longer
OPM	-2504%	-29%	14%	-863%	

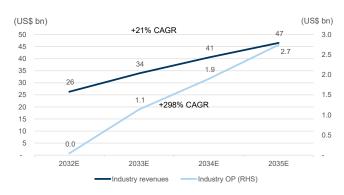
Source: Company data, Goldman Sachs Global Investment Research

### (7) Operating leverage? Increasing operating profits as business scales





Exhibit 24: Tier-1 cities: Operating leverage



Source: Goldman Sachs Global Investment Research

Source: Goldman Sachs Global Investment Research

We expect China's robotaxi industry to break-even in the OP level in Tier-1 cities by 2032E. Our unit economics analysis shows that robotaxis will achieve break even in the unit GM level by 2026E/ 2031E/ 2034E in Tier-1/Tier-2/ other cities. However, it takes longer to achieve scale efficiency at the operating income level. At break-even point, we expect robotaxi's R&D expenses to decrease to US\$7,800 per vehicle year, with SG&A expenses decreasing to US\$4,100 per vehicle year. For Tier-2 cities and others, we expect it to take a longer time to turn positive on the operating income level, considering a relatively small fleet size.

# Exhibit 25: Robotaxi in tier-1 cities: \$270,000 expenses on R&D and \$80,000 on SG&A per vehicle in 2025E

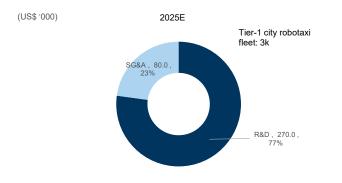
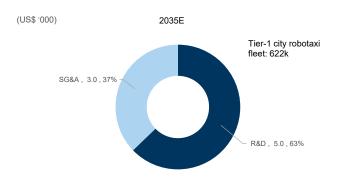


Exhibit 26: Robotaxi in tier-1 cities: \$5,000 expenses on R&D and \$3,000 on SG&A per vehicle in 2035E



Source: Company data, Goldman Sachs Global Investment Research

Source: Company data, Goldman Sachs Global Investment Research

**Operating leverage:** Tier-1 cities' industry revenues will grow at 21% CAGR from \$26bn to \$47bn in 2032-35E, and operating profits will grow faster at 298% CAGR from \$43m to \$2.7bn. As shown in our units economic analysis, 23% ~ 42% of COGS are variable - the relatively low variable costs would support the companies to improve profitability as it scales. Also, the increasing fleet size will quickly dilute the burden of R&D / SG&A spending, supporting robotaxis to achieve operating profits.

### (8) Downside risk? Profitability is sensitive to competition

Exhibit 27: Our sensitivity analysis on operating margin in tier-1 cities

The impact of changes in # of orders and ASP

2035 Operating margin in Tier-1 cities

	<u>'</u>			ASP per	order (US\$)			
		1.5	2	2.5	3	4.5	6	7.5
	4	-1303%	-952%	-742%	-601%	-368%	-251%	-181%
	9	-478%	-333%	-247%	-189%	-93%	-44%	-16%
က္	14	-264%	-173%	-118%	-82%	-21%	9%	27%
orders	19	-165%	-99%	-59%	-33%	12%	34%	47%
o Jo	24	-109%	-57%	-25%	-4%	30%	48%	58%
0#	29	-72%	-29%	-3%	14%	43%	57%	66%
	34	-47%	-10%	12%	27%	51%	63%	71%
	39	-28%	4%	23%	36%	57%	68%	74%
	44	-13%	15%	32%	44%	62%	72%	77%

Source: Company data, Goldman Sachs Global Investment Research

Competition will be a major risk to the industry's long-term profitability. While currently there are only a few players in the market, we see increasing interest from tech giants, traditional OEMs and ride hailing platform players to enter the business. In our base case, we expect tier-1 cities' robotaxis to enjoy 14% OPM by 2035E, with 29 orders per day and \$3 ASP per order. Nevertheless, there's downside risks to pricing and order volume should there be greater competition. Our sensitivity analysis shows that robotaxi players' profitability is sensitive to the changes in orders and ASPs: (1) If the ASP declines from \$3 to \$2.5 due to competition, the industry level OPM will decline to -3%. (2) If the # of orders per day declines from 29 to 24 due to competition, the industry level OPM will decline to -4%.

### (9) Downside risks? Accidents can damage reputation

Safety and accidents are key downside risks to the industry. From past experience, a fatal accident can impact the business by causing a loss of trust. Also, the overall adoption of robotaxi technology may be delayed if there is a significant accident, as it takes time to regain trust. While robotaxi makers have prioritized safety in vehicle designs and their daily operations, there remains a possibility of unforeseen risks. Robotaxi companies need to have emergency plan for accidents, building on-the-ground fast response teams to deal with emergencies and be responsible to its users.

### (10) Where to find Robotaxis? 10+ cities with Robotaxi services in China

### More than 10 cities in China with robotaxis available to the public (Exhibit 30).

Availability is expanding into more cities and operating areas. Nationwide, the current milestone for robotaxi players is to achieve *fare charging fully driverless* services, which will begin commercialization (fare charging) and establish the foundation of large scale deployment (fully driverless).

**Fully driverless in Beijing, Shanghai, Guangzhou, Shenzhen, Wuhan and Chongqing etc.** In Shenzhen, fully driverless robotaxis can operate in Nanshan district, one of center hubs of the city (such as Pony AI). In Beijing, fully driverless robotaxis operate in Yizhuang (Beijing Economic-Technological Development Area) with 225 square km, such as WeRide. In Guangzhou, fully driverless fare-charging services are in Nansha district; in Shanghai, fully driverless robotaxi services are open to the public. The fully driverless fare charging service is also available in Wuhan and Chongqing (such as Baidu Apollo).

Source: Company data, Data compiled by Goldman Sachs Global Investment Research

# (11) Policy progress? Supportive policies with more operating areas

Exhibit 31: Supportive policies for robotaxi from national to city level

National level policies Department	Policy name	Date (MM-YY)	Key points
Department		Date (WIW-11)	Provide systematic artificial intelligence services for key emerging fields such as
State Council	The 14th Five-Year Plan for the Development of	Jan-22	government services, smart cities, intelligent manufacturing, autonomous driving, and
	the Digital Economy		language intelligence.
Ministry of Industry and Information			Select intelligent connected vehicle products with autonomous driving functions that
Technology, Ministry of Public Security,	Notice on the pilot work of intelligent connected	Nov-23	meet the conditions for mass production and carry out pilot projects; for intelligent
Ministry of Housing and Urban-Rural	vehicle access and road access	1404-23	connected vehicle products that have obtained access, carry out on-road driving pilot
Development, Ministry of Transport			projects in limited areas.
Responsibility for autonomous driving	and accidents		
City	Policy name	Date	Key points
	Regulations on the Administration of Intelligent		If a fully autonomous smart connected car violates road traffic safety laws while there is no
Shenzhen	Connected Vehicles in Shenzhen Special	Jun-22	driver, the responsibility goes to the vehicle owner and manager.
	Economic Zone		
Shanghai	Regulations of Shanghai Pudong New Area on Promoting the Innovative Application of	Nov-22	The company to which the driverless smart connected car belongs shall first pay compensation and may seek reimbursement from the responsible autonomous driving
Shanghai	Driverless Intelligent Connected Vehicles	NOV-22	system developers, car manufacturers, equipment providers
			Autonomous driving vehicle manufacturers shall bear the main responsibility for the
Beijing	Beijing Autonomous Driving Vehicle Regulations	Jan-25	quality and production consistency of autonomous driving vehicles.
C			quality and production conditional of datastonians arrang remotes.
Supportive policies on road-test and co	Policy name	Date	Key points
Oity		Duto	
***	Wuhan City Intelligent Connected Vehicle Road	1 00	Remote driving demonstration application refers to the demonstration application and
Wuhan	Testing and Demonstration Application Management Implementation Rules	Jun-22	commercial pilot of intelligent connected vehicles carrying people, cargo or special operations with no human driver in the driving seat.
	Management implementation Rules		operations with no numan driver in the driving seat.
			Encourage the promotion and application of new technologies and products for intelligent
Wuhan	Wuhan Regulations on Promoting the	Nov-24	connected vehicles, and support road testing, demonstration applications, commercia
Transit	Development of Intelligent Connected Vehicles		pilots and commercial operations of intelligent connected vehicles
			For demonstration applications in public service fields such as sanitation cleaning, urban management, convenience services, public transportation, travel services, and logistics
Dailing	Ten measures to promote high-quality development of the intelligent connected vehicle	Nov-24	distribution, financial support of 6 yuan per kilometer will be provided based on the
Beijing	industry	NOV-24	test mileage, with a maximum annual support amount of 3 million yuan per
	madou y		enterprise.
			·
	Guangzhou Regulations on the Innovation and	Jan-25	The city supports intelligent connected vehicles to carry out commercial operations
Guangzhou	Development of Intelligent Connected Vehicles	Jan-25	based on sufficient verification through road testing and demonstration applications.

Source: Government websites, Data compiled by Goldman Sachs Global Investment Research

China's policy support for robotaxi is across national to city level.

■ **High-level national support:** In 2022, autonomous driving technology was listed in the 14th 'Five-Year Plan for the development of Digital Economy' by the state council. Back in 2023, four major ministries of the state established notice to promote the market and road access for autonomous driving vehicles.

- Clarify the responsibility. Local governments have been active in establishing policies on responsibilities for accidents, which some robotaxi players may have thought that was a major obstacle that had stopped the robotaxi from large scale development. For example in Shanghai, the government stated that the owner for the robotaxi should pay the compensation upfront and may see reimbursement from system developers, car manufacturers, equipment providers. Only when responsibilities are clarified, Robotaxi players can accurately measure their operation risks and manage their fleet accordingly.
- Supportive policies for road test and commercialization. Local governments are open to road test, pilot operations and even full commercialization of robotaxi, providing a supportive environment. Wuhan has already started allowing driverless (no human driver in the driving seat) vehicles to conduct demonstration application in 2022; Beijing provides financial support based on test mileage in 2024; and Guangzhou in 2025 supports robotaxi companies to start carrying out commercial operations.

Shenzhen Guangzhou Shanghai Beijing **Obtaining test license Testing with** passenger Open service to the public Suburb areas To/ from airports & railway stations City central areas City wide autonomous driving Intercity autonomous driving

Exhibit 32: Key milestones to achieve robotaxi services in China

Shanghai is still in non-faring charging demonstration stage

Source: Company data, Goldman Sachs Global Investment Research

**Major cities in China are opening more operating areas for robotaxi.** In the four tier-1 cities in China, robotaxis are only operated in predetermined areas, yet to achieve full city coverage. Some cities allow operations in suburbs, some allow several selected routes to connect Airports / Railway stations to the city center/ city suburban areas, and some have started to open up core areas of the city's urban area.

**Overseas expansions.** Apart from the domestic market, Chinese robotaxi players are exploring overseas markets. WeRide has obtained autonomous driving license in five countries (China, UAE, Singapore, France, United States) and is performing autonomous driving R&D, testing and operations in 10+ countries. Pony Al also recently announced it is among the first companies to get the robotaxi testing permit in Luxembourg. Pony Al has established an R&D center in the US, established technology partnership and deployment in South Korea, Saudi Arabia and UAE, and is partnering with ComfortDelGro with the aim to expand robotaxi deployment in different cities and countries.

## (12) Insurance support? Still in early stage of development

Insurance coverage is important for robotaxi operators and users to mitigate potential risks. Per our checks with the robotaxi players, currently insurance for robotaxis is still in the early stage of development:

- Insurance is a requirement. For example, in Beijing, the local government requires robotaxis to have Compulsory motor vehicle traffic accident liability insurance and carrier liability insurance. Meanwhile, the Beijing government supports insurance companies to work with robotaxi supply chain to come up with products that can more comprehensively cover the risks in robotaxi operations.
- Challenges in identifying liabilities. While more robotaxis are now driverless, there are still remote safety assistants who would be responsible for the monitoring per our checks, making it difficult to identify if faults lie with humans or the system. Moreover, multiple parties involved in robotaxi operations would further complicate liability identification. Per our supply chain checks, currently robotaxi owners and operators would bear the primary responsibility and coordinate with their insurance companies to pay the compensation. After the payment, owners/ operators can seek reimbursement from manufacturers and suppliers if they are found liable.
- Accident rate as a factor for insurance fees. Per comments from Robotaxi operators current data suggest that the accident rates of robotaxis are lower than traditional taxis, and therefore the pricing of robotaxi insurances should be lower than traditional ones. The coverage of risks are not including the risks of human drivers, such as drunk driving, etc.

### (13) Reasons to use Robotaxi? A new riding experience with entertainment

With technology enhancement, we expect the costs on hardware and software would continue to reduce, supporting large scale deployment and shortening passengers' waiting time. The enhancing technology could also bring better riding experience, for example, a normal driving speed that allows passengers to arrive at the destinations at the same time if they choose human-driven shared mobility.

Exhibit 33: Robotaxi for different user groups across white collars, family etc.

### Robotaxi user profile



White collars (1-2 ppl per car)

Time: Monday to Friday, 7am to 9 am & 5pm to 8pm Kev scenarios: Daily logistics, from home to office, or from metro station to office Service requirement: Silent environment for work and meeting



(2-5 ppl per car)

Time: Saturday to Sunday, all day **Key scenarios:** Family event for lunch/ dinner, or outing Service requirement:

Entertainment (game, cartoon) for children and family group



The aged

Time: Monday to Sunday. 7am to 7pm Kev scenarios: Daily routine, from home to supermarket, food market, or hospital Service requirement: Clean environment. services with patience



(2-4 ppl per car)

Time: Holiday, all day Key scenarios: Sightseeing, logistics across different destinations (airport, hotel) Service requirement: Services with fair taxi fare, travelling suggestions

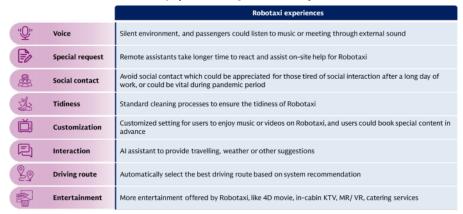


Time: All Day Key scenarios: Daily logistics Service requirement: Services offered with different languages

Source: Company data, Goldman Sachs Global Investment Research

Reasons to use Robotaxis includes: (1) for fleet owners, robotaxi could transform their idle assets to assets generating cash flow and could theoretically operate longer hours as it is operated by robots. Robotaxi could also avoid the potential difficulties to hire human drivers in the long term, as other jobs could be more attractive, (2) for passengers, robotaxis could avoid drowsy driving, dangerous driving, detours, social contact (which could be appreciated for those tired of social interaction after a long day of work, or could be vital during pandemic periods), etc.

Exhibit 34: Robotaxi as a mobility space to bring enhanced experience



Source: Company data, Goldman Sachs Global Investment Research

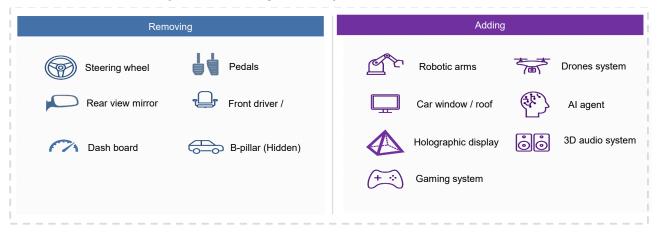
A new riding experience: Robotaxi allows vehicles to be redesigned to better fit passengers' needs. For example, a wider room for 4D movie, KTV, gaming, MR/VR or catering services for passengers. Passengers could also book movie or music in advance before using Robotaxi services, or customize the services based on their previous preferences. Robotaxi could also come with robotic arms, which can help handle the luggage, or even making a cup of tea for the passenger.

### (14) Future form factors? Without steering wheels, but with robotic arms, Al and drones

Without human drivers, the future car design would change focus from the

driver's features to passengers' in-vehicle experience. Traditional components like steering wheels, rear view mirrors, dash boards and pedals are likely to disappear, leaving the car computer to take full control of the vehicle. In our view, there may be no need for front seats, leaving more space for passengers. WeRide has already introduced an innovative design of hidden B pillar, integrated with the car doors, allowing a large space for getting in and out of the vehicle.

Exhibit 35: Future robotaxis will likely have different designs from today's vehicles



Source: Company data, Goldman Sachs Global Investment Research

We expect innovative designs for future robotaxis. Car windows and roofs could be turned into displays, with the transparent OLED / Micro LED technology that has been evolving in recent years. Holographic 3D projections could be ideal for in-car display, turning the whole cabin into an immersive virtual space. All agents could enhance human-machine interaction, assisting passengers in scheduling or route planing. A drone launching system on the car, similar to what BYD and DJI have presented (Link), could allow passengers to take photos and videos and get deliveries along the way.

Exhibit 36: Pony Al's Gen7 Robotaxi models



Provided by Pony AI

Source: Company data

Exhibit 37: WeRide's Robobus in new form factor



Provided by WeRide

Source: Company data

### (15) Future market segmentation? Widening choice of car models

Widening car models for passengers to choose: As robotaxi is still in the early stage,

currently there is no distinguished service segmentation for different groups of targeted users. We expect robotaxi companies to begin with daily commute individual users, and later launch a range of services from cost-effective to high-end robotaxi models with different interior designs and functionalities to improve the user experience, and the fare charging of a single ride would also range from low to high.

Exhibit 38: Potential future robotaxi models and functionalities

Potential future robotaxi models	Model	Passenger capacity	<b>( Functionality</b>	Vehicle Price (US\$ k)
For individual user	SUV / sedan	4-8	Mainstream models to offer individual users cost-effective daily communtes	14 - 25
For family	SUV / sedan	4-8	Equipped with gaming devices, movie projector, and KTV funtion to enhance the family's travel enjoyment	15 - 35
For business	MPV / mini bus	8 - 15	Equipped with sound proof materials, microphone, meeting slide projector, and large size screens to enable the high quality business meeting	25 - 65
For aged / disabled user	Sedan	1 - 3	Barrier-free design with automatic door and ramp to help disabled / aged users get in / off the $\mbox{\it car}$	14 - 25
For luxury service	SUV / sedan	1 - 2	High-end models with large space and luxury interior materials, equipped with AI models to follow users' command	50 - 65

Vehicle prices of future robotaxi models are GSe (based on current taxi-hailing models' price segmentation in China)

Source: Company data, Goldman Sachs Global Investment Research

## (16) Potential up-scaling methods? Collaboration with riding platforms

Exhibit 39: Five types of platforms to call for robotaxis in China

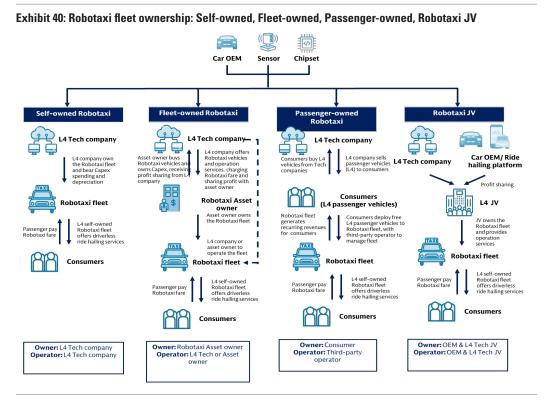
	In-house App	Taxi-hailing platform	Map platform	Fintech platform	Social media platform
	© E	TIME	<b>&gt;</b>	支	<b>%</b>
User volume	Pony AI: ~0.2m registered	34.5m registered	30 - 800m MAU	890m MAU	1,385m MAU
Downloads Available cities	<15	>300	>360	>360	>360
Taxi-hailing operators integrated	1	>5	>10	>10	>10
How to call for a robotaxi	- Run the App - Set the pick-up and drop-off location	- Run the App - Choose robotaxi - Set the drop-off location	- Run the App - Choose taxi-hailing - Set up pick-up and drop-off location - Choose Robotaxi	- Run the App - Search the robotaxi mini software - Set the pick-up and drop-off location	- Run the App - Open the Service tab - Choose taxi-hailing - Set the pick-up and drop-off location - Choose Robotaxi

Source: Company data, Data complied by Goldman Sachs Global Investment Research

There are five available platforms for users to call for robotaxis. Each robotaxi operator has its in-house App, whose user volume is still small. Traditional shared mobility platforms (taxi-hailing apps, map apps, Fintech app's mini programs, social media) have also integrated robotaxi-hailing function, although the feature is not yet displayed at the most obvious place.

We expect the integration of robotaxi into the traditional taxi-hailing platforms as an efficient way to promote usage. Traditional platforms' large user base and mature platform design can bring exposure to robotaxi fleets. Although robotaxi vendors usually need to share ~10% of the GMV (gross merchandise value) with the platforms, the cost of acquiring users from scratch can be higher.

# (17) Potential up-scaling methods? Shared-ownership to encourage adoption



Source: Company data, Goldman Sachs Global Investment Research

We reviewed different potential business models of Robotaxi fleets, and note that the industry started with the Self-owned business model, then migrated to fleet-owned or passenger-owned with improving Unit Economics per Robotaxi.

(1) Self-owned Robotaxi fleet: L4 companies own and operate the fleet, which is asset heavy. (2) Fleet-owned Robotaxi fleet: Asset owners purchase Robotaxi vehicles and bear the depreciation cost. L4 companies either operate the fleet and share the profit with asset owners, or purely offer virtual driver solution for asset owners by charging annual subscription fee. (3) Passenger-owned Robotaxi: Individual consumers buy L4 vehicles for daily life usage, and they could deploy their vehicles to Robotaxi fleet to generate revenues. (4) Robotaxi JV: L4 companies set up JV with car OEMs or ride-hailing platform to own and operate the Robotaxi fleet, then share profits.

### (18) What to improve? Density and fleet coverage

Exhibit 41: Fleet density: Robotaxi vs. non-robotaxi

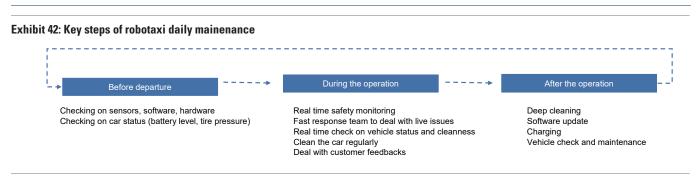
	Shanghai	Beijing	Shenzhen	Guangzhou						
	Traditional taxi fleet in 2024 (k units)									
	282	399	148	189						
٩		Robotaxi fleet	in 2024 (k units)							
	0.1	0.2	0.1	0.1						
		Long-term residents	in 2023 (mn of people)							
	Around 24.9	Around 21.9	Around 17.8	Around 18.8						
		Traditional tax	i per mn people							
	11,339	18,225	8,303	10,032						
â		Robotaxi pe	er mn people							
<del>即五</del> 第	4	10	7	12						

Long-term residents are 2023 data from Provincial Statistics Bureau, Traditional and Robotaxi fleet sizes are GSe, Traditional taxi includes taxi fleet and ride-hailing fleet

Source: Goldman Sachs Global Investment Research

**Rising density to shorten waiting time:** Robotaxi's development in China is still at the initial stage with only a few vehicles offering service to the public. The average available robotaxi per million people is lower than traditional taxi fleet (taxi and ride-hailing) in China's major cities (Shanghai, Beijing, Shenzhen, Guangzhou). Currently, pricing promotion is one of the main measures to attract initial user base. We expect more robotaxis deployment in major cities in the next few years, attracting more users.

### (19) What to improve? Cleaning and maintenance



Source: Company data, Goldman Sachs Global Investment Research

### As the robotaxi fleet scales up, maintenance becomes increasingly important

Apart from daily vehicle maintenance such as checking the battery and replacing the tires, robotaxis require extra maintenance for sensitive sensors as well as upgrades of software. Due to the longer operating hours, robotaxis would need more frequent checks to ensure safety. As there are no drivers in the vehicles, remote safety monitors would need to track the vehicles in real time and a fast response team would need to stand by in case of any emergency.

### Cleanliness a key factor for consumer adoption

The operators can install in-vehicle cameras to monitor cleanliness, and call back the vehicle for cleaning when needed. Extra cleaning fees can be charged to users where appropriate. The operators can also install air circulation and purifier/sterilizer systems in the robotaxi to maintain fresh air.

Robotaxi operators may outsource some of their daily maintenance to third-party experts due to its complexity and labour intensity. For example, Waymo has been partnered with Avis since 2017. Intelligent cleaning robotics can also be a potential solution in the future, as showcased by Tesla in a video that a robot can clean the interior of the vehicle automatically.

### (20) What to improve? Algorithm enhanced by world model

World Model Pre-training Static **Environment** Car operation Generator 4D Prompts **RL** training (Static large Obstacles Reinforcement Simulated base environment/ Generator learning) scenarios Navigation) model **ADV** action generator Human feedback Companies launched World Model/ VLM Model PONY B WeRide

Exhibit 43: Enhanced autonomous driving data leverage both driving data and simulated driving scenarios

Source: Company data

From human driver data to simulated scenarios to scale-up: The smart driving industry is upgrading from human data driven L2 algorithm to World Model/VLM (Visual Language Model) that use simulated driving scenarios for Reinforcement Learning training. L4 autonomous driving requires the virtual driver to outperform human drivers, and therefore needs generative data from world models, in our view. Many companies have launched in-house World Model or VLM Model for driving functions with high autonomous level (Exhibit 43). Currently, some companies only use real-world data for pre-training and rely more on simulation from World Model, and some companies leverage more from human driving mileage and use simulated driving scenario for compensation.

# (21) How to evaluate safety? Sensors, driving styles and emergency measures

A full set of sensors including Lidar, cameras and radars. These major three types of sensors are used for different ranges (25m-300m) and scenarios (raining or foggy). Compared to L2 passenger cars that come with 1-2 front view cameras and 0-1 Lidar, a typical robotaxi would have 10+ cameras for different range of views, multiple Lidar to achieve a wide angle, and multiple radars to detect short range/ long range. For example, WeRide's GXR model has 20+ sensors to ensure safety.

**Style of driving is also a major consideration.** The robotaxi algorithm has different characteristics, similar to those of different human drivers, which are the combined result of the robotaxi supplier's preference and its training data-set. A safe algorithm can brake early and slowly, strictly follow the traffic rules, accurately communicate with the other drivers on the road (e.g. turning on the left-turn/ right turn signals), and slow down for pedestrians and non-motor vehicles.

Exhibit 44: Pony Al's robotaxi in traffic



Provided by Pony AI

Source: Company data

**Exhibit 45: Pony Al's driverlss operations** 



Provided by Pony Al

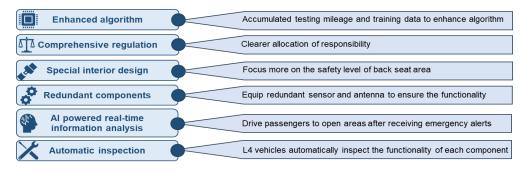
Source: Company data

**Emergency measures.** Extra emergency measures need to be added inside and outside the robotaxi. For example, WeRide's GXR has a safety button inside the vehicle that can ask the car to park slowly, safety hammer for emergency and safety door handle for evacuation. We believe it could be helpful for the robotaxi to have an emergency call button to contact the control center, external sirens for passengers to warn pedestrians, and a door button that can unlock and open all car doors at the same time.

# (22) How to enhance safety? Combined effort in software, hardware, and regulations

We expect the robotaxi industry to enhance safety through: (1) Algorithm updates; (2) More comprehensive regulations; (3) Interior design; (4) Redundant components; (5) Al powered real-time information analysis; (6) Automatic inspection.

### Exhibit 46: How to improve the overall safety of robotaxi



Source: Goldman Sachs Global Investment Research

### Disclosure Appendix

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# MINDCRAFT: OUR THEMATIC DEEP DIVES

#### Artificial Intelligence



#### **Humanoid Robots**



China in Transition



China Resilience



Japan Value in Action



The Ecosystem of EV



The Ecosystem of Batteries



Tracking Greater China's activity



Autonomous driving



China Property



China Consumer



CHIPS Act Impact



Investing in India



Carbonomics



China Grid Tech



Healthcare Innovation



Suppy Chain Shifts



Trade and tariffs



Market Concentration



Top of Mind



**Balanced Bear** 



Market Cycles



Tracking the Consumer



Korea Value in Action



Cybersecurity and Defense



Computing Advances



Magnificent 7



**Top Projects** 



China Battery Energy Storage System (BESS)



Future of Energy



Power Demand



**Black Womenomics** 



Music in the Air



Robotics & Automation



Understanding China's Statistics



Clean Hydrogen



Green Capex



ESG



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